

Parametrized Surfaces

March 22, 2010

Surfaces

Surface: A two dimensional object in space.

Locally: each point P of S has a patch around it that (shape-wise) looks like an open patch in the plane.

Examples:

Surfaces

Surface: A two dimensional object in space.

Locally: each point P of S has a patch around it that (shape-wise) looks like an open patch in the plane.

Examples:

Graph surfaces:

Let $D \subset \mathbb{R}^2$ be an open set and $f: D \rightarrow \mathbb{R}$ a continuous function.

Then

$$S = \{(x, y, z) \mid (x, y) \in D, z = f(x, y)\}$$

is a surface: for every point (x_0, y_0, z_0) on S , there exists an open disk B centered at (x_0, y_0) and included in D . Then the patch

$$E = \{(x, y, z) \mid (x, y) \in B, z = f(x, y)\}$$

is an open patch on S around P and f identifies E with B .

Surfaces

Surface: A two dimensional object in space.

Locally: each point P of S has a patch around it that (shape-wise) looks like an open patch in the plane.

Examples:

Planes:

S : plane through P_0 and parallel to directions \mathbf{u} and \mathbf{v}

$$\mathbf{r} = \mathbf{r}_0 + s\mathbf{u} + t\mathbf{v} ,$$

Function $\mathbf{F}: \mathbb{R}^2 \rightarrow \mathbb{R}^3$,

$$\mathbf{F}(s, t) = \mathbf{r}_0 + s\mathbf{u} + t\mathbf{v}$$

globally identifies S with the plane \mathbb{R}^2 .

- ▶ $S \ni P \iff$ pair of coordinates (s, t) ;
- ▶ The vectors $\mathbf{F}_s = \mathbf{u}$ and $\mathbf{F}_t = \mathbf{v}$ are non-collinear.

Local parametrizations

A (differentiable) local parametrization: function $\mathbf{F}: D \rightarrow \mathbb{R}^3$,

▶ defined on an open subset $D \subset \mathbb{R}^2$;

▶ given by

$$\mathbf{F}(s, t) = (f_1(s, t), f_2(s, t), f_3(s, t))$$

such that

- ▶ \mathbf{F} is 1-1: each point in the image has a unique pair of coordinates;
- ▶ The components f_1, f_2, f_3 are differentiable functions from D to \mathbb{R} .
- ▶ The vectors \mathbf{F}_s and \mathbf{F}_t are non-collinear.

Image of \mathbf{F} : surface in \mathbb{R}^3 .

Example

Let R be fixed and $\mathbf{F}: (0, \pi) \times (0, 2\pi) \rightarrow \mathbb{R}^3$ be given by

$$\mathbf{F}(s, t) = \langle R \sin s \cos t, R \sin s \sin t, R \cos s \rangle .$$

Image of \mathbf{F} :

Example

Let R be fixed and $\mathbf{F}: (0, \pi) \times (0, 2\pi) \rightarrow \mathbb{R}^3$ be given by

$$\mathbf{F}(s, t) = \langle R \sin s \cos t, R \sin s \sin t, R \cos s \rangle .$$

Image of \mathbf{F} : open subset on the sphere $S_R(O)$.

Example

Let R be fixed and $\mathbf{F}: (0, \pi) \times (0, 2\pi) \rightarrow \mathbb{R}^3$ be given by

$$\mathbf{F}(s, t) = \langle R \sin s \cos t, R \sin s \sin t, R \cos s \rangle .$$

Image of \mathbf{F} : open subset on the sphere $S_R(O)$.

- ▶ \mathbf{F} is defined on the open subset

Example

Let R be fixed and $\mathbf{F}: (0, \pi) \times (0, 2\pi) \rightarrow \mathbb{R}^3$ be given by

$$\mathbf{F}(s, t) = \langle R \sin s \cos t, R \sin s \sin t, R \cos s \rangle .$$

Image of \mathbf{F} : open subset on the sphere $S_R(O)$.

- ▶ \mathbf{F} is defined on the open subset $D = (0, \pi) \times (0, 2\pi) \subset \mathbb{R}^2$;

Example

Let R be fixed and $\mathbf{F}: (0, \pi) \times (0, 2\pi) \rightarrow \mathbb{R}^3$ be given by

$$\mathbf{F}(s, t) = \langle R \sin s \cos t, R \sin s \sin t, R \cos s \rangle .$$

Image of \mathbf{F} : open subset on the sphere $S_R(O)$.

- ▶ \mathbf{F} is defined on the open subset $D = (0, \pi) \times (0, 2\pi) \subset \mathbb{R}^2$;
- ▶ \mathbf{F} is 1 – 1:

Example

Let R be fixed and $\mathbf{F}: (0, \pi) \times (0, 2\pi) \rightarrow \mathbb{R}^3$ be given by

$$\mathbf{F}(s, t) = \langle R \sin s \cos t, R \sin s \sin t, R \cos s \rangle .$$

Image of \mathbf{F} : open subset on the sphere $S_R(O)$.

- ▶ \mathbf{F} is defined on the open subset $D = (0, \pi) \times (0, 2\pi) \subset \mathbb{R}^2$;
- ▶ \mathbf{F} is 1 – 1: $\mathbf{F}(s_1, t_1) = \mathbf{F}(s_2, t_2) \iff (s_1, t_1) = (s_2, t_2)$;

Example

Let R be fixed and $\mathbf{F}: (0, \pi) \times (0, 2\pi) \rightarrow \mathbb{R}^3$ be given by

$$\mathbf{F}(s, t) = \langle R \sin s \cos t, R \sin s \sin t, R \cos s \rangle .$$

Image of \mathbf{F} : open subset on the sphere $S_R(O)$.

- ▶ \mathbf{F} is defined on the open subset $D = (0, \pi) \times (0, 2\pi) \subset \mathbb{R}^2$;
- ▶ \mathbf{F} is 1 – 1: $\mathbf{F}(s_1, t_1) = \mathbf{F}(s_2, t_2) \iff (s_1, t_1) = (s_2, t_2)$;
- ▶ Components of \mathbf{F} are differentiable:

Example

Let R be fixed and $\mathbf{F}: (0, \pi) \times (0, 2\pi) \rightarrow \mathbb{R}^3$ be given by

$$\mathbf{F}(s, t) = \langle R \sin s \cos t, R \sin s \sin t, R \cos s \rangle .$$

Image of \mathbf{F} : open subset on the sphere $S_R(O)$.

- ▶ \mathbf{F} is defined on the open subset $D = (0, \pi) \times (0, 2\pi) \subset \mathbb{R}^2$;
- ▶ \mathbf{F} is 1 – 1: $\mathbf{F}(s_1, t_1) = \mathbf{F}(s_2, t_2) \iff (s_1, t_1) = (s_2, t_2)$;
- ▶ Components of \mathbf{F} are differentiable:

$$f_1(s, t) = R \sin s \cos t, \quad f_2(s, t) = R \sin s \sin t, \quad f_3(s, t) = R \cos s .$$

Example

Let R be fixed and $\mathbf{F}: (0, \pi) \times (0, 2\pi) \rightarrow \mathbb{R}^3$ be given by

$$\mathbf{F}(s, t) = \langle R \sin s \cos t, R \sin s \sin t, R \cos s \rangle .$$

Image of \mathbf{F} : open subset on the sphere $S_R(O)$.

- ▶ \mathbf{F} is defined on the open subset $D = (0, \pi) \times (0, 2\pi) \subset \mathbb{R}^2$;
- ▶ \mathbf{F} is 1 – 1: $\mathbf{F}(s_1, t_1) = \mathbf{F}(s_2, t_2) \iff (s_1, t_1) = (s_2, t_2)$;
- ▶ Components of \mathbf{F} are differentiable:

$$f_1(s, t) = R \sin s \cos t, \quad f_2(s, t) = R \sin s \sin t, \quad f_3(s, t) = R \cos s .$$

- ▶ \mathbf{F}_s and \mathbf{F}_t are non-collinear:

Example

Let R be fixed and $\mathbf{F}: (0, \pi) \times (0, 2\pi) \rightarrow \mathbb{R}^3$ be given by

$$\mathbf{F}(s, t) = \langle R \sin s \cos t, R \sin s \sin t, R \cos s \rangle .$$

Image of \mathbf{F} : open subset on the sphere $S_R(O)$.

- ▶ \mathbf{F} is defined on the open subset $D = (0, \pi) \times (0, 2\pi) \subset \mathbb{R}^2$;
- ▶ \mathbf{F} is 1 – 1: $\mathbf{F}(s_1, t_1) = \mathbf{F}(s_2, t_2) \iff (s_1, t_1) = (s_2, t_2)$;
- ▶ Components of \mathbf{F} are differentiable:

$$f_1(s, t) = R \sin s \cos t, \quad f_2(s, t) = R \sin s \sin t, \quad f_3(s, t) = R \cos s .$$

- ▶ \mathbf{F}_s and \mathbf{F}_t are non-collinear:

$$\mathbf{F}_s = \langle R \cos s \cos t, R \cos s \sin t, -R \sin s \rangle$$

$$\mathbf{F}_t = \langle -R \sin s \sin t, R \sin s \cos t, 0 \rangle$$

$$|\mathbf{F}_s \times \mathbf{F}_t| = R^2 \sin s \neq 0$$

Parametrized surfaces

A subset S in space is a *smooth surface* if

- ▶ For every point P of S , there is a smooth local parametrization of an open patch on S around P ;
- ▶ When images of two local parametrizations overlap on S , the two local parametrizations should be compatible.

Examples:

Parametrized surfaces

A subset S in space is a *smooth surface* if

- ▶ For every point P of S , there is a smooth local parametrization of an open patch on S around P ;
- ▶ When images of two local parametrizations overlap on S , the two local parametrizations should be compatible.

Examples:

- ▶ The plane $ax + by + cz = d$ is a surface;

Parametrized surfaces

A subset S in space is a *smooth surface* if

- ▶ For every point P of S , there is a smooth local parametrization of an open patch on S around P ;
- ▶ When images of two local parametrizations overlap on S , the two local parametrizations should be compatible.

Examples:

- ▶ The plane $ax + by + cz = d$ is a surface;
- ▶ The sphere $x^2 + y^2 + z^2 = R^2$ is a surface.

Parametrized surfaces

A subset S in space is a *smooth surface* if

- ▶ For every point P of S , there is a smooth local parametrization of an open patch on S around P ;
- ▶ When images of two local parametrizations overlap on S , the two local parametrizations should be compatible.

Examples:

- ▶ The plane $ax + by + cz = d$ is a surface;
- ▶ The sphere $x^2 + y^2 + z^2 = R^2$ is a surface.

Non-example:

The cone $z^2 = x^2 + y^2$ is not globally a surface

Parametrized surfaces

A subset S in space is a *smooth surface* if

- ▶ For every point P of S , there is a smooth local parametrization of an open patch on S around P ;
- ▶ When images of two local parametrizations overlap on S , the two local parametrizations should be compatible.

Examples:

- ▶ The plane $ax + by + cz = d$ is a surface;
- ▶ The sphere $x^2 + y^2 + z^2 = R^2$ is a surface.

Non-example:

The cone $z^2 = x^2 + y^2$ is not globally a surface, because there is no patch around $(0, 0, 0)$ that looks like an open set in the plane.

Level Surfaces as Parametrized Surfaces

Let $f: \mathbb{R}^3 \rightarrow \mathbb{R}$ be a differentiable function.

- ▶ P is a *critical point* if $(\nabla f)(P) = 0$;
- ▶ $c \in \mathbb{R}$ is a *critical value* if

$$f^{-1}(c) = \{(x, y, z) \mid f(x, y, z) = c\}$$

contains a critical point.

- ▶ If c is not a critical value then it is a *regular value*.

Implicit Function Theorem \implies

If c is a regular value taken by f , then $f^{-1}(c)$ is a smooth surface.

Examples:

Level Surfaces as Parametrized Surfaces

Let $f: \mathbb{R}^3 \rightarrow \mathbb{R}$ be a differentiable function.

- ▶ P is a *critical point* if $(\nabla f)(P) = 0$;
- ▶ $c \in \mathbb{R}$ is a *critical value* if

$$f^{-1}(c) = \{(x, y, z) \mid f(x, y, z) = c\}$$

contains a critical point.

- ▶ If c is not a critical value then it is a *regular value*.

Implicit Function Theorem \implies

If c is a regular value taken by f , then $f^{-1}(c)$ is a smooth surface.

Examples:

For $f(x, y, z) = ax + by + cz$ with a, b, c not all zero,

- ▶ All points P are regular points
- ▶ All values d are regular;
- ▶ $f^{-1}(d)$ is a smooth surface: the plane $ax + by + cz = d$.

Level Surfaces as Parametrized Surfaces

Let $f: \mathbb{R}^3 \rightarrow \mathbb{R}$ be a differentiable function.

- ▶ P is a *critical point* if $(\nabla f)(P) = 0$;
- ▶ $c \in \mathbb{R}$ is a *critical value* if

$$f^{-1}(c) = \{(x, y, z) \mid f(x, y, z) = c\}$$

contains a critical point.

- ▶ If c is not a critical value then it is a *regular value*.

Implicit Function Theorem \implies

If c is a regular value taken by f , then $f^{-1}(c)$ is a smooth surface.

Examples:

For $f(x, y, z) = x^2 + y^2 - z^2$,

- ▶ $(0, 0, 0)$ is the only critical point $\implies 0 = f(0, 0, 0)$ is the only critical value.
- ▶ $H = f^{-1}(1)$ is a smooth surface: $x^2 + y^2 - z^2 = 1$, a hyperboloid with one sheet.

Surfaces of Revolution

- ▶ C be a curve in the (x, z) -plane;
- ▶ S be the surface obtained by revolving C around the z -axis.

Parametrization of $C \implies$ parametrization of S

Surfaces of Revolution

- ▶ C be a curve in the (x, z) -plane;
- ▶ S be the surface obtained by revolving C around the z -axis.

Parametrization of $C \implies$ parametrization of S

$I \ni u \rightarrow (f(u), g(u))$: smooth, regular parametrization of C

Surfaces of Revolution

- ▶ C be a curve in the (x, z) -plane;
- ▶ S be the surface obtained by revolving C around the z -axis.

Parametrization of $C \implies$ parametrization of S

$I \ni u \rightarrow (f(u), g(u))$: smooth, regular parametrization of C

$\mathbf{F}: I \times (0, 2\pi) \rightarrow \mathbb{R}^3$ given by

$$\mathbf{F}(u, v) = (f(u) \cos v, f(u) \sin v, g(u))$$

parametrizes the part of S not in the (x, z) -plane.

Surfaces of Revolution

- ▶ C be a curve in the (x, z) -plane;
- ▶ S be the surface obtained by revolving C around the z -axis.

Parametrization of $C \implies$ parametrization of S

$I \ni u \rightarrow (f(u), g(u))$: smooth, regular parametrization of C

$\mathbf{F}: I \times (0, 2\pi) \rightarrow \mathbb{R}^3$ given by

$$\mathbf{F}(u, v) = (f(u) \cos v, f(u) \sin v, g(u))$$

parametrizes the part of S not in the (x, z) -plane.

$$|\mathbf{F}_u \times \mathbf{F}_v| = |f| \sqrt{(f')^2 + (g')^2},$$

hence \mathbf{F} is a smooth parametrization if $f(u) \neq 0$ for all u .

Surfaces of Revolution

- ▶ C be a curve in the (x, z) -plane;
- ▶ S be the surface obtained by revolving C around the z -axis.

Parametrization of $C \implies$ parametrization of S

$I \ni u \rightarrow (f(u), g(u))$: smooth, regular parametrization of C

$\mathbf{F}: I \times (0, 2\pi) \rightarrow \mathbb{R}^3$ given by

$$\mathbf{F}(u, v) = (f(u) \cos v, f(u) \sin v, g(u))$$

parametrizes the part of S not in the (x, z) -plane.

$$|\mathbf{F}_u \times \mathbf{F}_v| = |f| \sqrt{(f')^2 + (g')^2},$$

hence \mathbf{F} is a smooth parametrization if $f(u) \neq 0$ for all u .

Geometrically: the curve C shouldn't intersect the z -axis.

Example: Torus

Let C be the circle

- ▶ in the (x, z) -plane,
- ▶ of radius r ,
- ▶ with center at $(R, 0, 0)$ such that $R > r$.

Parametrization of C :

Example: Torus

Let C be the circle

- ▶ in the (x, z) -plane,
- ▶ of radius r ,
- ▶ with center at $(R, 0, 0)$ such that $R > r$.

Parametrization of C : $u \rightarrow (R + r \cos u, r \sin u)$; $0 \leq u \leq 2\pi$.

Corresponding surface of revolution: S

Example: Torus

Let C be the circle

- ▶ in the (x, z) -plane,
- ▶ of radius r ,
- ▶ with center at $(R, 0, 0)$ such that $R > r$.

Parametrization of C : $u \rightarrow (R + r \cos u, r \sin u)$; $0 \leq u \leq 2\pi$.

Corresponding surface of revolution: S , *torus* (the surface of a doughnut)

Parametrization of an open patch on the torus:

Example: Torus

Let C be the circle

- ▶ in the (x, z) -plane,
- ▶ of radius r ,
- ▶ with center at $(R, 0, 0)$ such that $R > r$.

Parametrization of C : $u \rightarrow (R + r \cos u, r \sin u)$; $0 \leq u \leq 2\pi$.

Corresponding surface of revolution: S , *torus* (the surface of a doughnut)

Parametrization of an open patch on the torus:

$$\mathbf{F}(u, v) = ((R + r \cos u) \cos v, (R + r \cos u) \sin v, r \sin u) .$$

Example: Torus

Let C be the circle

- ▶ in the (x, z) -plane,
- ▶ of radius r ,
- ▶ with center at $(R, 0, 0)$ such that $R > r$.

Parametrization of C : $u \rightarrow (R + r \cos u, r \sin u)$; $0 \leq u \leq 2\pi$.

Corresponding surface of revolution: S , *torus* (the surface of a doughnut)

Parametrization of an open patch on the torus:

$$\mathbf{F}(u, v) = ((R + r \cos u) \cos v, (R + r \cos u) \sin v, r \sin u) .$$

To make \mathbf{F} to be 1-1 we restrict the domain to $(0, 2\pi) \times (0, 2\pi)$.

The image of F is

Example: Torus

Let C be the circle

- ▶ in the (x, z) -plane,
- ▶ of radius r ,
- ▶ with center at $(R, 0, 0)$ such that $R > r$.

Parametrization of C : $u \rightarrow (R + r \cos u, r \sin u)$; $0 \leq u \leq 2\pi$.

Corresponding surface of revolution: S , *torus* (the surface of a doughnut)

Parametrization of an open patch on the torus:

$$\mathbf{F}(u, v) = ((R + r \cos u) \cos v, (R + r \cos u) \sin v, r \sin u) .$$

To make \mathbf{F} to be 1-1 we restrict the domain to $(0, 2\pi) \times (0, 2\pi)$.

The image of F is S minus two circles:

- ▶ the vertical circle $x^2 + z^2 = 1, y = 0$ ($u \neq 0$)
- ▶ the horizontal circle $x^2 + y^2 = (R + r)^2, z = 0$ ($v \neq 0$).

Tangent Plane

Let $\mathbf{F}: D \rightarrow \mathbb{R}^3$, $\mathbf{F}(u, v) = (f(u, v), g(u, v), h(u, v))$ be a local parametrization of a surface S ,

$P = \mathbf{F}(u_0, v_0)$: point on S .

The *tangent plane* to S at P :

- ▶ passes through P ;
- ▶ contains vectors tangent at P to curves on S passing through P .

Tangent Plane

Let $\mathbf{F}: D \rightarrow \mathbb{R}^3$, $\mathbf{F}(u, v) = (f(u, v), g(u, v), h(u, v))$ be a local parametrization of a surface S ,

$P = \mathbf{F}(u_0, v_0)$: point on S .

The *tangent plane* to S at P :

- ▶ passes through P ;
- ▶ contains vectors tangent at P to curves on S passing through P .

We get curves on S from curves in D , using \mathbf{F} :

$$\gamma(t) = \mathbf{F}(u(t), v(t)) = (f(u(t), v(t)), g(u(t), v(t)), h(u(t), v(t)))$$

$$\gamma(0) = P \implies u(0) = u_0 \text{ and } v(0) = v_0$$

$$\gamma'(0) = u'(0)\mathbf{F}_u(u_0, v_0) + v'(0)\mathbf{F}_v(u_0, v_0)$$

Every tangent vector at P is a linear combination of \mathbf{F}_u and \mathbf{F}_v .

Tangent Plane

Let $\mathbf{F}: D \rightarrow \mathbb{R}^3$, $\mathbf{F}(u, v) = (f(u, v), g(u, v), h(u, v))$ be a local parametrization of a surface S ,

$P = \mathbf{F}(u_0, v_0)$: point on S .

The *tangent plane* to S at P :

- ▶ passes through P ;
- ▶ contains vectors tangent at P to curves on S passing through P .

Tangent plane: parallel to directions $\mathbf{F}_u(u_0, v_0)$ and $\mathbf{F}_v(u_0, v_0)$.

Normal to the plane tangent to S at $P = \mathbf{F}(u_0, v_0)$:

$$\mathbf{N}(u_0, v_0) = \mathbf{F}_u(u_0, v_0) \times \mathbf{F}_v(u_0, v_0)$$

Equation for the tangent plane:

$$(\mathbf{r} - \mathbf{F}(u_0, v_0)) \cdot \mathbf{N}(u_0, v_0) = 0 .$$

A vectorial parametric equation for the line normal to S at P is

$$\mathbf{r}(t) = \mathbf{F}(u_0, v_0) + t\mathbf{N}(u_0, v_0) .$$

Example

Let $\mathbf{F}(u, v) = (u \cos v, u \sin v, e^{2u-4})$ and $P = \mathbf{F}(2, \pi/3)$.

Example

Let $\mathbf{F}(u, v) = (u \cos v, u \sin v, e^{2u-4})$ and $P = \mathbf{F}(2, \pi/3)$.

$$\mathbf{F}_u(u, v) = \langle \cos v, \sin v, 2e^{2u-4} \rangle \implies \mathbf{F}_u(2, \pi/3) = \left\langle \frac{1}{2}, \frac{\sqrt{3}}{2}, 2 \right\rangle$$

$$\mathbf{F}_v(u, v) =$$

Example

Let $\mathbf{F}(u, v) = (u \cos v, u \sin v, e^{2u-4})$ and $P = \mathbf{F}(2, \pi/3)$.

$$\mathbf{F}_u(u, v) = \langle \cos v, \sin v, 2e^{2u-4} \rangle \implies \mathbf{F}_u(1, \pi/3) = \left\langle \frac{1}{2}, \frac{\sqrt{3}}{2}, 2 \right\rangle$$

$$\mathbf{F}_v(u, v) = \langle -u \sin v, u \cos v, 0 \rangle \implies \mathbf{F}_v(1, \pi/3) = \langle -\sqrt{3}, 1, 0 \rangle$$

Example

Let $\mathbf{F}(u, v) = (u \cos v, u \sin v, e^{2u-4})$ and $P = \mathbf{F}(2, \pi/3)$.

$$\mathbf{F}_u(u, v) = \langle \cos v, \sin v, 2e^{2u-4} \rangle \implies \mathbf{F}_u(1, \pi/3) = \left\langle \frac{1}{2}, \frac{\sqrt{3}}{2}, 2 \right\rangle$$

$$\mathbf{F}_v(u, v) = \langle -u \sin v, u \cos v, 0 \rangle \implies \mathbf{F}_v(1, \pi/3) = \langle -\sqrt{3}, 1, 0 \rangle$$

$$\mathbf{N}(1, \pi/3) =$$

Example

Let $\mathbf{F}(u, v) = (u \cos v, u \sin v, e^{2u-4})$ and $P = \mathbf{F}(2, \pi/3)$.

$$\mathbf{F}_u(u, v) = \langle \cos v, \sin v, 2e^{2u-4} \rangle \implies \mathbf{F}_u(1, \pi/3) = \left\langle \frac{1}{2}, \frac{\sqrt{3}}{2}, 2 \right\rangle$$

$$\mathbf{F}_v(u, v) = \langle -u \sin v, u \cos v, 0 \rangle \implies \mathbf{F}_v(1, \pi/3) = \langle -\sqrt{3}, 1, 0 \rangle$$

$$\mathbf{N}(1, \pi/3) = \mathbf{F}_u(1, \pi/3) \times \mathbf{F}_v(1, \pi/3) \implies \mathbf{N}(1, \pi/3) = -2\mathbf{i} - 2\sqrt{3}\mathbf{j} + 2\mathbf{k}$$

and since $\mathbf{F}(2, \pi/3) = \langle 1, \sqrt{3}, 1 \rangle$, an equation for the tangent plane is

Example

Let $\mathbf{F}(u, v) = (u \cos v, u \sin v, e^{2u-4})$ and $P = \mathbf{F}(2, \pi/3)$.

$$\mathbf{F}_u(u, v) = \langle \cos v, \sin v, 2e^{2u-4} \rangle \implies \mathbf{F}_u(1, \pi/3) = \left\langle \frac{1}{2}, \frac{\sqrt{3}}{2}, 2 \right\rangle$$

$$\mathbf{F}_v(u, v) = \langle -u \sin v, u \cos v, 0 \rangle \implies \mathbf{F}_v(1, \pi/3) = \langle -\sqrt{3}, 1, 0 \rangle$$

$$\mathbf{N}(1, \pi/3) = \mathbf{F}_u(1, \pi/3) \times \mathbf{F}_v(1, \pi/3) \implies \mathbf{N}(1, \pi/3) = -2\mathbf{i} - 2\sqrt{3}\mathbf{j} + 2\mathbf{k}$$

and since $\mathbf{F}(2, \pi/3) = \langle 1, \sqrt{3}, 1 \rangle$, an equation for the tangent plane is

$$(\langle x, y, z \rangle - \langle 1, \sqrt{3}, 1 \rangle) \cdot \langle -2, -2\sqrt{3}, 2 \rangle = 0$$

$$-2(x - 1) - 2\sqrt{3}(y - \sqrt{3}) + 2(z - 1) = 0 \iff x + \sqrt{3}y - z = 3.$$

Example

Let $\mathbf{F}(u, v) = (u \cos v, u \sin v, e^{2u-4})$ and $P = \mathbf{F}(2, \pi/3)$.

$$\mathbf{F}_u(u, v) = \langle \cos v, \sin v, 2e^{2u-4} \rangle \implies \mathbf{F}_u(1, \pi/3) = \left\langle \frac{1}{2}, \frac{\sqrt{3}}{2}, 2 \right\rangle$$

$$\mathbf{F}_v(u, v) = \langle -u \sin v, u \cos v, 0 \rangle \implies \mathbf{F}_v(1, \pi/3) = \langle -\sqrt{3}, 1, 0 \rangle$$

$$\mathbf{N}(1, \pi/3) = \mathbf{F}_u(1, \pi/3) \times \mathbf{F}_v(1, \pi/3) \implies \mathbf{N}(1, \pi/3) = -2\mathbf{i} - 2\sqrt{3}\mathbf{j} + 2\mathbf{k}$$

and since $\mathbf{F}(2, \pi/3) = \langle 1, \sqrt{3}, 1 \rangle$, an equation for the tangent plane is

$$(\langle x, y, z \rangle - \langle 1, \sqrt{3}, 1 \rangle) \cdot \langle -2, -2\sqrt{3}, 2 \rangle = 0$$

$$-2(x - 1) - 2\sqrt{3}(y - \sqrt{3}) + 2(z - 1) = 0 \iff x + \sqrt{3}y - z = 3.$$

Parametric equations for the normal line are

Example

Let $\mathbf{F}(u, v) = (u \cos v, u \sin v, e^{2u-4})$ and $P = \mathbf{F}(2, \pi/3)$.

$$\mathbf{F}_u(u, v) = \langle \cos v, \sin v, 2e^{2u-4} \rangle \implies \mathbf{F}_u(1, \pi/3) = \left\langle \frac{1}{2}, \frac{\sqrt{3}}{2}, 2 \right\rangle$$

$$\mathbf{F}_v(u, v) = \langle -u \sin v, u \cos v, 0 \rangle \implies \mathbf{F}_v(1, \pi/3) = \langle -\sqrt{3}, 1, 0 \rangle$$

$$\mathbf{N}(1, \pi/3) = \mathbf{F}_u(1, \pi/3) \times \mathbf{F}_v(1, \pi/3) \implies \mathbf{N}(1, \pi/3) = -2\mathbf{i} - 2\sqrt{3}\mathbf{j} + 2\mathbf{k}$$

and since $\mathbf{F}(2, \pi/3) = \langle 1, \sqrt{3}, 1 \rangle$, an equation for the tangent plane is

$$(\langle x, y, z \rangle - \langle 1, \sqrt{3}, 1 \rangle) \cdot \langle -2, -2\sqrt{3}, 2 \rangle = 0$$

$$-2(x - 1) - 2\sqrt{3}(y - \sqrt{3}) + 2(z - 1) = 0 \iff x + \sqrt{3}y - z = 3.$$

Parametric equations for the normal line are

$$x = 1 - 2t, \quad y = \sqrt{3} - 2\sqrt{3}t, \quad z = 1 + 2t.$$